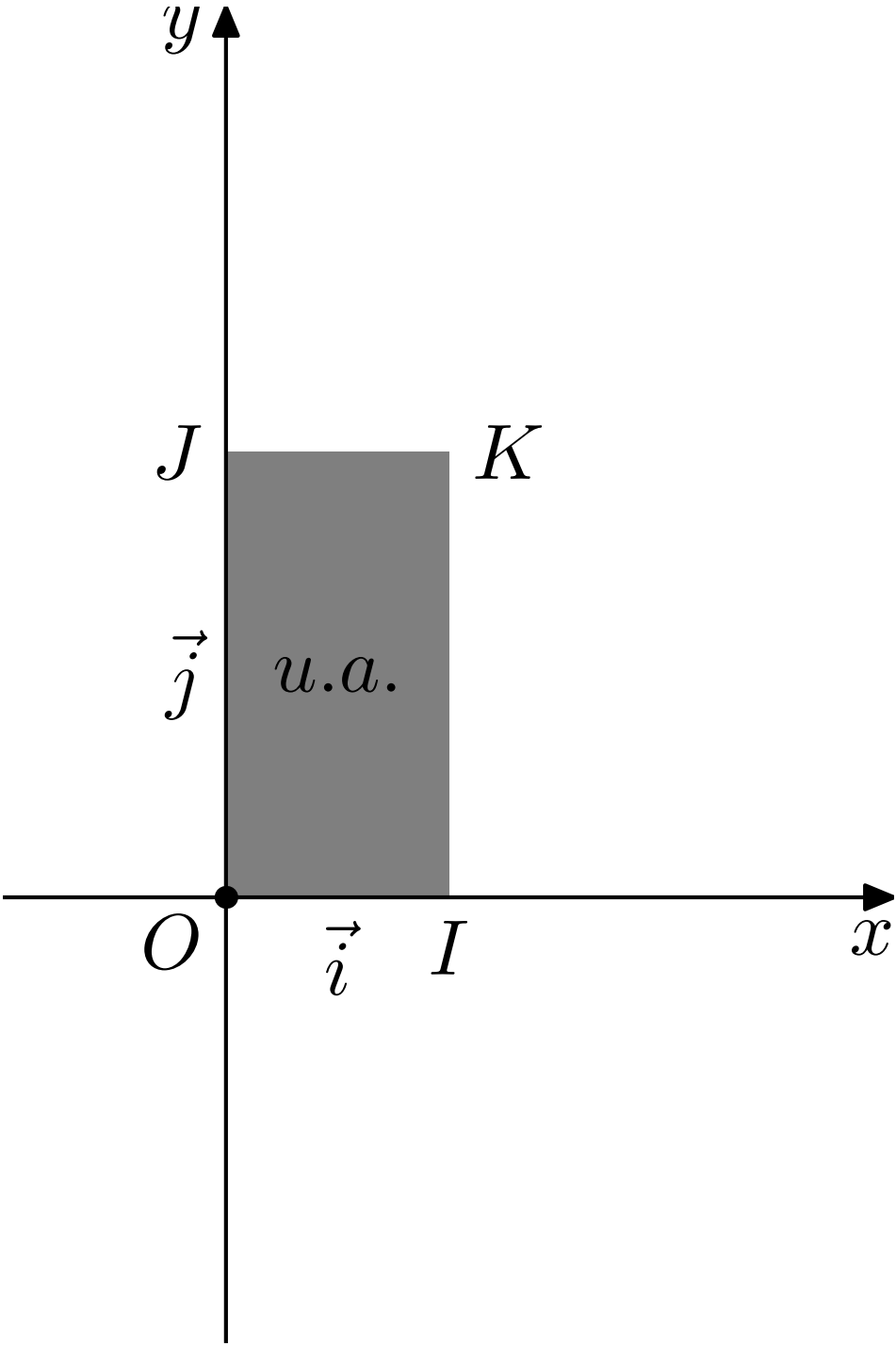
y
J
K
$\vec{j}$
$u.a.$
O
$\vec{i}$
I
x